IDENTIFICATION OF PATCHOULI PLANTS USING LANDSAT-8 SATELLITE IMAGERY AND IMPROVED K-MEANS METHOD

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ABSTRACT

To maintain the availability of the patchouli plants required monitoring the spread of patchouli plantation. This study performed the identification of patchouli plant through Landsat-8 satellite imagery and Improved K-Means method. Improved was done on this study include the process of determining the initial cluster by specifying the closeness between the data and the determination of the number of cluster (K) by using the histogram equalization technique. The result of internal criteria testing shows that determining the number of clusters using the histogram is less effective because it produces the lower value of the silhouette. On almost all image data test found the best value of the silhouette's coefficient is 75.089% at K=2 and data in February. Furthermore, based on the results of testing the external criteria known the highest purity value in February data with a number of cluster 5 is 0.6829268. The test results also show that the use of the Improved K-Means on the Landsat-8 image has not been able to recognize the difference patchouli plants with other crops due to the limited resolution of imagery data and also the minimum number and variation of test data. But, visually the patchouli plant cluster is found for February data while the age of the rice crop surrounding the patchouli is still in the early phase of planting.

Keywords: patchouli plants, Landsat-8 imagery, Improved K-Means, histogram equalization

1. INTRODUCTION

One of essential crop in Indonesia which has huge potential is Lemongrass scented (Cymbopogon nardus) and (Pogostemon cablin). patchouli Both plants produce essential oils for raw materials of perfume industry, insecticides, and medical. Essential plant growth is influenced by some factors such as intensity of sunlight, the height of land above sea level, and the climate (Kardinan, 2005). In Indonesia, there have been many essential plant cultivated commercially. According to the data of Ministry of Agriculture, the land area of essential plantation crops particularly patchouli reach 29,783 hectares (Directorate General of Plantations, 2013). Based on the data of

this area extent, Indonesia was able to supply 90% of the essential needs of the world's or 1600 tons per year (Ministry of Agriculture, 2015). Therefore, the Government should keep pushing the production of essential oils remain stable or even increased. Consequently, the position of Indonesia on essential oil world market can last. To that end, the availability of raw materials in the form of essential crops needs to be monitored. To maintain the availability of essential plants are required monitoring the distribution of essential crops plantation.

Monitoring the area of these essential crop plantations could be done using remote sensing techniques. This technique makes it possible to see the state of an object, area, or a particular phenomenon without visiting the area directly (Lillesand, Kiefer, & Chipman, 2008).

In previous research, multispectral satellite imagery is used to map the agricultural land of rice plant in China. Monitoring rice crops utilizes satellite imagery from Landsat 8 OLI. This research method using Spatial-Temporal Probabilistic Models (TSPM) to distinguish the image of rice farmland with the image of the other. The results of this research can provide the agricultural area of rice in China (Sun, Xie, Zhang, Zhu, Wei, & Yuan, 2014). The other research conducted by Xiaoa et al (2005) applied the method of Temporal Profile Analysis to find out the area of rice crops. This study uses MODIS satellite images from EOS Terra. The composite image used was taken during the breeding period. cropping, and after the harvest. The probability calculation is done on each region by calculating the Normalized Difference Vegetation Index (NDVI), Enhanced Vegetation Index (EVI), and Land Surface Water Index (LSWI). This study used NLCD2000 dataset to validate the results from the MODIS image. The results of calculation by using the same algorithm on these two datasets shows that on NLCD2000 generate 560,257 km square of rice fields, while on the MODIS generate 420,572 km square of rice fields (Xiao, et al., 2005).

Both these studies perform recognition of rice plant based on spectral patterns of rice plant during its growth phase. It is very possible because at each phase, rice crops have greatly different color information. At the beginning of the planting up to 2 months, the plant's color is green, then at the time of flowering will turn yellowish and finally on the phases of the harvest being Brown. Thus the NDVI could produce a quiet accurate recognition. As for the spectral pattern of patchouli plant is very different from the rice plant. The difference in the color of leaves ranging from planting until harvest time has not seen clearly if recognized using NDVI. Thus it takes a different approach in doing the recognition. This research used Improved K-Means method to perform the identification of patchouli plant.

K-Means working with grouped data based on characteristic equation. This method is simple and has a high performance (Ayech & Ziou, 2016). But, the number of cluster must be determined before. In addition, a different initial of centre cluster may produce different cluster. To that end, some research doing various approaches to improving the performance of the k-means method (Khanmohammadi, Adibeig, & Shanehbandy, 2017; Yao, Duan, Li, & Wang, 2013).

Khanmohammadi, et al. (2017) propose a hybrid method that combines kharmonic means and overlapping k-means algorithms (KHM-OKM) to overcome overlapping information on medical dataset and sensitivity to the initial cluster centroids. The results shows the outperforms of proposed method than the original OKM algorithm.

Yao, et al (2012) propose a new method to improve the accuracy and stability of fish image segmentation. This study combine the KK-means clustering segmentation algorithm and mathematical morphology. The results show that the algorithm can separate between the fish image and the complex backgrounds.

The improved has done in this study is automatic initialization of cluster center and the number of cluster. The determination of the initial cluster is by specifying the closeness between the data the determination the number of cluster by using the histogram equalization techniques.

2. METHOD

In General, the flow of patchouli plants identification process shown in Figure 1. Input is a Landsat-8 image has been cropped in accordance with the study area. Next is pre-processing using Journal of Environmental Engineering & Sustainable Technology (JEEST) Vol. 03 No. 02, November 2016, Pages 70-77

histogram equalization and the extraction of the histogram to get the number of peak histogram for initialization values of K in K-Means. After that is calculation the closeness between the data to get initial cluster value. The process continued with the clustering method using Modified K-Means. Then, choose the cluster that is identified as patchouli plants and displays the output in the form of cluster label on each pixel. The descriptions of each steps is described in the following section.



Figure 1 General flow of identification process

2.1 Histogram Equalization

Histogram equalization is a quite optimal technique of contrast sharpening. The result is depending on to the shape of the original image histogram. Histogram equalization provides more poignancy in appearance between the block object (Gonzalez & Woods, 2008). This technique has three stages, namely:

1. Calculate Probability Mass Function (PMF) of histogram formed using equation 1.

$$PMF = \frac{frequency}{total \ pixel} \tag{1}$$

1. Calculate Cumulative Distribution Function (CDF) from PMF without doing *sorting* on histogram frequency by using equation 2.

$$CDF(n) = \frac{level \ frequency + \sum_{i=0}^{n} frequency(i)}{total \ pixel}$$
(2)

2. Multiply CDF with the value of the second maximum pixel to obtain new histogram on image.

The new histogram will have pixels with new value, so the frequency of some pixels will increase.

The data used in this study have different qualities. Some data has almost same pixel value, so that the contrast stretching using this technique is necessary for more easily recognize the different of pixel values.

2.2 K-Means Clustering

K-Means clustering is unsupervised learning that grouping input data without knowing the target class. The characteristics of each cluster are determined by the value of the center point (centroid) (MacQueen, 1967). Steps of K-Means algorithm is as follows:

- 1. Initialize the number of cluster (K) and dataset will be grouped.
- 2. Initialize initial centroid that can be . taken randomly from the dataset
- 3. Calculate the average value of each formed cluster. This value is the average value of all record within the cluster and called centroid.
- 4. Entering each datum into a nearest centroid.
- 5. Change the centroid of each cluster by re-calculates the average of cluster.
- 6. Re-enter each datum into cluster as step 4.
- 7. Repeat steps 5 and 6 to produce a stable centroid.

Centroid value obtained from the average value of the data that is a member of a cluster. This value is calculated for each centroid feature, so that each feature on each cluster has own centroid value. Centroid value is calculated by equation 3.

$$\mu_{k} = \frac{1}{N_{k}} \sum_{q=1}^{N_{k}} x_{q}$$
(3)

Where μ_k is centroid of k cluster, N_k is the amount of data at k cluster and X_q is q data at k cluster.

Euclidean Distance to determine the distance between the centroid and data can be calculated by equation 4

$$d_{ij} = \sqrt{\sum_{k=1}^{p} (x_{ik} - x_{jk})}$$
(4)

Where d_{ij} is the distance between object i and object j, P is the data dimension, X_{ik} is the coordinate of object i at k dimension, X_{jk} is coordinate of object j at k dimension.

2.3 Improved K-Means

Improved K-Means in this study lies in the modification of determining the number of clusters and initial centroid. The number of clusters is determined by counting the number of peak from histogram average (Yao, Duan, Li, & Wang, 2013).

The initial centroid is initialized by calculating the distance of each pixel to another. Then use improved K-Means to determine the point of being used as a centroid. Steps for initializing the initial centroid are as follows:

- 1. Calculate the distance between each pixel to another by using *Euclidean Distance*.
- 2. Calculate distance v_j for object j by using equation 5.

$$V_{j} = \sum_{i=1}^{n} \frac{d_{ij}}{\sum_{l=1}^{n} d_{il}}$$
(5)

4. Take n highest point from v_j to be used as initial *centroid*.

2.4 Silhouette Coefficient

Silhouette coefficient was used to assess the quality of clusters based on internal criteria. The evaluation by calculate the similarity of each cluster member in the cluster (Kogan, 2006). Steps to calculate silhouette coefficient is as follows:

- 1. Calculate the average value of Euclidean Distance from datum i to the other in the same cluster.
- 2. Calculate the average value of Euclidean Distance from datum i to the other at different cluster. Find the smallest value from all average value to set as neighbor cluster.
- 3. Calculate Silhouette coefficient by using equation 6.

$$s(i) = \frac{b(i) - a(i)}{\max\{a(i), b(i)\}}$$
(6)

Where s(i) is silhouette coefficient i, a(i) is the average distance i with the other data on the same cluster, b(i) is the minimum value of the average distance i with other data on other cluster

The silhouette coefficient value is - $1 \le s$ (i) ≤ 1 . The larger the value of silhouette coefficient, the better the clustering is done.

2.5 Purity

Purity is used to evaluate the clustering based on external criteria. Calculating the value of purity required actual class data in each record. Each cluster is inserted into a class that has a frequency at most. Accuracy is obtained by calculating the pixel which is labeled in accordance with the real situation divided the total number of pixels (Deepa & Revathy, 2012). Purity can be calculated using equation 7.

$$purity(\Omega, C) = \frac{1}{N} \sum_{k} \max_{j} \left| \omega_{k} \cap c_{j} \right|$$
(7)

3. Sort the value of v_i in ascending.

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Where $\Omega = \{\omega_1, \omega_2, ..., \omega_k\}$ is *cluster set*, C = $\{c_1, c_2, ..., c_j\}$ is class set, N is an amount of data.

Purity value is ranging from 0 to 1. A clustering is said to be worse if the purity close to 0, and is said to be good if it has a value close to 1 (Deepa & Revathy, 2012).

3. DATA

This study uses two types of data, ie Landsat-8 satellite image OLI/TIRS Path/Row 118/66 and ground truth data.

The image data used are time series data acquired by satellites on every month starting from February to June 2015. The resolution of Landsat-8 is 30x30 m for each pixel. This images then are cropped of 42x41 pixels to take the area around the study area in the district of Kesamben, Blitar. A portion of this area is planted patchouli with area of 0.8 hectares. Specifications of satellite imagery used in this study are shown in Tabel 1.

Tabel 1 Specification of Landsat-8 imagery data

Date of Acquired	Time of Acquired	Cloud Coverage (%)
2015-02-24	02:35:58.0503736Z	27.03
2015-03-28	02:35:38.8368115Z	9.62
2015-04-29	02:35:25.7222365Z	34.00
2015-05-15	02:35:10.0371358Z	16.75
2015-06-16	02:35:27.3889844Z	9.08
2015-07-18	02:35:43.8314918Z	8.83

This study uses three of the total 11 existing spectral, namely BAND 3 Visible Green, BAND 4 Visible Red and BAND 5 Near Infrared. The raw data were then processed into data that can be used by K-Means.

Ground truth data is taken in real terms in the field and used for testing the accuracy of the system. This data was obtained by field observation in the pathcouli garden in Kesamben Subdistrict, Blitar. Ground truth data is represented in the form of images that have the same resolution as satellite imagery.

4. RESULD AND DISCUSSION

This study performs testing of internal criteria and external criteria to determine performance of Improved K-Means algorithm.

4.1 The Result of Internal Criteria Testing

Internal criteria testing intended to determine the best number of clusters using the silhouette coefficient. This test uses six dataset image with the number of clusters is determined by the amount of image histogram (k). Besides that, it is also tested the other number of cluster to determine the effectiveness of using the histogram in the selection of the number of clusters. The number of clusters used in these tests ranging from 2 to (k-1). The test results are shown in Table 2. The result of using histogram is blocked by color and presented at the first line for each data.

Month of Dataset	Month of Cluster Dataset		Silhouette Coefficient	% of Silhouette Coefficient	
February	11	17	0,151487	57,57434	
	2	7	0,501783	75,08913	
	3	22	0,409176	70,4588	
	4	29	0,276072	63,8036	
	5	24	0,331857	66,59285	
	6	28	0,238806	61,94028	
	7	36	0,271834	63,59168	
	8	51	0,238811	61,94055	
	9	25	0,19031	59,51552	
	10	30	0,089815	54,49074	
March	9	52	0,304909	65,24547	
	2	5	0,490425	74,52125	
	3	14	0,435199	71,75995	
	4	13	0,225673	61,28364	
	5	29	0,23039	61,51949	
	6	19	0 27985	63 99252	

Tabel 2 The result of internal criteria testing

Month of Dataset	Cluster	Iteration	Silhouette Coefficient	% of Silhouette Coefficient	
	7	25	0,279438	63,97191	
	8	32	0,276578	63,82888	
	18	37	0,247563	62,37815	
	2	11	11 0,454482		
	3	8 0,294645		64,73225	
	4	22 0,311183		65,55915	
April	5	13	13 0,359866		
Артт	6	26	0,354707	67,73537	
	7	34	0,217087	60,85434	
	8	35	0,308593	65,42963	
	9	51	0,277278	63,86388	
	10	25	0,3274	66,37002	
	11	29	0,275796	63,78978	
	2	17	0,180354	59,01772	
	3	12	0,444787	72,23937	
	4	23	0,147451	57,37256	
May	5	56	0,310375	65,51877	
wiay	6	20	0,310662	65,5331	
	7	20	20 0,210869		
	8	22	64,33416		
	9	36	36 0,274681		
	10	22	0,297544	64,87719	
	30	37	-0,1662	41,69012	
	2	6	0,430012	71,50058	
June	3	14	0,356946	67,84729	
	4	20	0,342249	67,11243	
	5	34	0,383888	69,19441	
	6	22	0,249778	62,48888	
	7	29	0,32482	66,24098	
	8	7	0,294928	64,74638	
	9	36 0,284115		64,20574	
	10	49 0,249691		62,48455	
	11	31	0,263357	63,16787	
	12	46	0,26297	63,1485	
	13	30	0,260568	63,02841	
Iuly	5	16	-0,60609	19,6955	
	2	9	0,073238	53,66189	
July	3	12	0,05185	52,59248	
	4	23	-0,66492	16,75379	

Table 2 show the silhouette coefficient for each dataset is varies even though it is tested at the same number of clusters. Silhouette coefficient value for dataset on July is significantly below than the other dataset. Even when using the initialization number of cluster by histogram only generate 19.6955%. The highest silhouette coefficient obtained is 75.08913%, which is tested on February dataset with the number of cluster 2.

Silhouette coefficient value changes due to differences in cluster membership generated by the K-Means clustering. The different on membership cause differences in the average distance of each pixel to another pixel.

This test only uses pixel value as parameter therefore it need further analysis to be associated with the identification of essential crops. Changes in the value of the pixel data for different months is quite large, this is due to weather conditions, solar lighting, the age of patchouli planting, the age of the rice planting, transplanting age on the other crop, and land use change.

In February data and the number of cluster 2, the result of clustering has high quality due to striking color differences of the young age rice plant and the building. The composite image has a similar pattern when compared to the clustering image, especially for the visible similarities of the buildings and plants. The image of the building cluster shown by the yellow color and the rice crop is indicated by the pink color.



Composite image

Clustering image

Figure 2 The composite image and clustering image on February data

4.2 Result of External Criteria Testing

External criteria testing used to test the purity of the cluster to the actual class.

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Actual data class used in this test was obtained from field observation as described in the previous section.

The external criteria testing uses 5 image dataset from February to June. Dataset in July is not used because it produces a low silhouette coefficient value. Each dataset was tested using 2 to 6 of clusters. The test results of purity can be seen in Tabel 3.

No	Month	Cluster Number	Purity	Purity (%)
1		2	0,6724739	67,25%
	F 1	3	0,6788618	67,89%
	February	4	0,6718931	67,19%
		5	0,6829268	68,29%
		6	0,670151	67,02%
		2	0,6538908	65,39%
		3	0,6614402	66,14%
2	March	4	0,6480836	64,81%
		5	0,6771196	67,71%
		6	0,6649245	66,49%
	April	2	0,4703833	47,04%
		3	0,481417	48,14%
3		4	0,518583	51,86%
		5	0,5156794	51,57%
		6	0,5319396	53,19%
4	May	2	0,4889663	48,90%
		3	0,543554	54,36%
		4	0,5638792	56,39%
		5	0,562137	56,21%
		6	0,5423926	54,24%
5	June	2	0,4785134	47,85%
		3	0,562137	56,21%
		4	0,5609756	56,10%
		5	0,5528455	55,28%
		6	0,5667828	56,68%

Tabel	3	The	result	of	purity	v testing
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Based on Tabel 3 is known that the highest purity is 0.6829268 at the February dataset with cluster number 5. The lowest one is occurred in April dataset with the number of cluster 2 which produces purity value 0.4703833.

Purity value for February and March datasets is above 0.6 because the age of the rice planting is still young as described above on internal analysis criteria. Here, the rice plant is dominates because it has very large area. The dominance of the rice plant led to a class dominated in almost the entire cluster. Therefore the purity test does not find cluster is dominated by a class of patchouli plant. Patchouli is quite difficult to recognize because it has a similar color to rice plants. However, when observed visually more closely it will be found a few clusters of patchouli.

On April to June, the patchouli and rice plants are growing older. At this age, visually the color of patchouli plant increasingly red and rice plant growing yellow. Different visual changes that occur for these two plantations are apparently not capable captured by the satellite sensors in visible green composite BAND, visible red BAND and near infrared BAND. The difference between the pixel value of the plants are still thin so that the recognition by the improved K-Means method is still bad and produce lower purity value, which is below 0.6. This is mainly due to patchouli crop area is very small and its position adjacent to the quite spacious area of rice crop.

5. CONCLUSION

Based on the results of testing that was done, we conclude that initialization the initial number of clusters using the histogram peak number does not produce optimal clustering quality. The greatest coefficient silhouette produced by K-Means clustering is only 75.08913% when testing using a dataset on February and the number of cluster 2. Furthermore, the result of external criteria testing shows the fluctuative of the purity value for different number of clusters. The results is also shown that the improved K-Means can not optimally identify the patchouli plant based on satellite imagery due to the limited number of test data and the limited resolution of Landsat-8 image. However, the few clusters of patchouli can be identified while observed on February data.

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